# A SIMPLE QUASI-LINEAR PURSUIT PROBLEM* 

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#### Abstract

A class of differential games is delineated, in which the main pursuit operator $T_{t^{*}}$ $/ 1,2 /$ is computed analytically. The support function of set $r_{i}{ }^{*}(M)$ is written out in explicit form. It is proved that for this class of games the optimal pursuit time coincides with the maximin pursuit time /l-5/introduced by Kelendzheridze. A sufficient condition for the completion of pursuit in Kelendzheridze's time is obtained for a linear differential game. The closeness of this condition to the necessary condition is proved. The paper borders on the investigations in /l-10/.


1. Let the motion of a vector $z$ in an $n$-dimensional Euclidean space $R^{n}=E$ be described by the vector differential equation

$$
\begin{equation*}
d z / d t=\lambda(v) z-F(u, v) ; \quad u \in P \subset R^{p}, \quad v \in Q \subset R^{q} \tag{1.1}
\end{equation*}
$$

( $u, v$ are control parameters, $P$ and $Q$ are compacta in finite-dimensional spaces: $F: P \times Q \rightarrow E$ and $\lambda: Q \rightarrow R^{1}$ are continuous mappings) and by the convex closed terminal set $M$. The statement of the pursuit problem in game (1.1), the objectives, the information available to the players have been defined in $/ 4 /$. The general theory of pursuit has been constructed in $/ 1,2 /$, reducing the study of pursuit problem (1.1) to the investigation of the structure of an operator $T_{t}{ }^{*}: 2^{E} \rightarrow 2^{E}$ (in contrast to $/ 2 /$ we use an asterisk instead of a tilde)

$$
\begin{gathered}
T_{\varepsilon}(X)=\bigcap_{v^{*} \in v} \bigcup_{\tau \in[0, \varepsilon]}\left(f_{v^{*}}(\tau) X+\int_{0^{\tau}}^{\tau} f_{v^{*}}(s) P(v(s)) d s\right), T_{\omega_{t}}(X)=T_{\delta_{m}}\left(T_{\delta_{m-1}}\left(\ldots\left(T_{\delta_{1}}(X)\right) \ldots\right)\right) ; \quad T_{t^{*}}(X)=\bigcap_{\omega_{1} \in \mathcal{Q}_{1}} T_{\omega_{t}}(X) \\
f_{v^{*}}(\tau)=\exp \left(-\int_{0}^{\tau} \lambda(v(s)) d s\right) ; \quad P(v)=\operatorname{conv} F(P, v)
\end{gathered}
$$

Here $V$ is the set of all measurable controls $v^{*}=\left\{v(s) \in Q, s \in R^{1}\right\}, \Omega_{t}$ is the set of all partitions $\omega_{t}=\left\{0<\delta_{1}<\delta_{1}+\delta_{2}<\ldots<\delta_{1}+\ldots+\delta_{m}=t\right\}$ of interval $[0, t]$ (cf. $/ 2,5 /$ ). The operator

$$
\begin{gather*}
\Theta_{\varepsilon}: 2^{E} \rightarrow 2^{E} ; \quad \Theta_{\varepsilon}(X)=\bigcap_{v \in Q} \Gamma(\varepsilon, X, v), \quad \Gamma(\varepsilon, X, v)=\bigcup_{\tau \in[0, \varepsilon]}(f(\tau, v) X+\gamma(\tau, v) P(v))  \tag{1.2}\\
f(\tau, v)=\exp (-\tau \lambda(v)) ; \gamma(\tau, v)=\int_{0}^{\tau} f(s, v) d s, \quad \Theta_{t}^{*}(X)=\bigcap_{\omega_{t} \in Q_{!}} \Theta_{\delta_{m}}\left(\Theta_{\delta_{m-1}}\left(\ldots\left(\Theta_{\delta_{1}}(X)\right) \ldots\right)\right)
\end{gather*}
$$

was introduced in /l,2/.
A fundamental theorem was proved in $/ 1 /:$ for any closed $X \subset E$ and for $t \geqslant 0 T_{t}^{*}(X)=$ $\theta_{t}{ }^{*}(X)$.

In the present paper we present conditions sufficient for the fulfillment of the equalities

$$
\begin{equation*}
T_{\mathrm{e}}{ }^{*}(M)=T_{\mathrm{E}}(M)=\theta_{\mathrm{e}}(M) \tag{1.3}
\end{equation*}
$$

The equalities (1.3) were first proved for the case $\lambda(v)=0, F(u, v)=u-v, \quad P$ and $Q$ are convex compacta in $E$, in $/ 3 /$.

Lemma 1. In order that (1.3) be fulfilled it is necessary and sufficient that.

$$
\begin{equation*}
\Theta_{\varepsilon_{1}}\left(\Theta_{\varepsilon_{2}}(M)\right)=\Theta_{\varepsilon_{1}+\varepsilon_{2}}(M), \quad \forall \varepsilon_{1} \geqslant 0, \quad \varepsilon_{2} \geqslant 0 \tag{1.4}
\end{equation*}
$$

Indeed, (1.4) follows from (1.3) and the semigroup property $/ 2 /$ of operator $T_{t^{*}}$ Conversely,if (1.4) is fulfi!led, then by induction $\Theta_{\omega_{\mathcal{e}}}(M)=\Theta_{\varepsilon}(M)$ for any $\omega_{\varepsilon} \in \Omega_{\mathbb{E}^{*}}$ It remains to make use of the fundamental theorem

$$
T_{e}{ }^{*}(M) \subset_{-} T_{e}(M) \subset \theta_{e}(M)=\int_{\Omega_{\varepsilon}} \theta_{\omega_{\varepsilon}}(M)=T_{e}^{*}(M)
$$

We observe that the inclusion of the left-hand side of (1.4) into the right always holds $/ 3,6 \%$
2. Let $X \subset E, \psi \in E$. We set

$$
W(X ; \psi)=\sup _{x \in X}(x \cdot \psi) ; \quad K(X)=\{\psi \in E: W(X ; \psi)<+\infty\}
$$

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$(W(X ; \psi)$ is the support function of set $X)$. Everywhere below we assume that $M$ and $X$ are convex closed sets in $E$.

Lemma 2. For all $\varepsilon \geqslant 0, v \in Q$ the set $\Gamma(\varepsilon, X, v)$ is convex and closed, and

$$
\Gamma(\varepsilon, X, v)=B(\varepsilon, X, v), \quad B(\varepsilon, X, v)=\operatorname{conv}(X \cup(f(\varepsilon, v) X+\gamma(\varepsilon, v) P(v)))
$$

The support function $W^{\varepsilon}(X, v ; \psi)$ of set $\Gamma(\varepsilon, X, v)$ equals

$$
W^{\mathrm{e}}(X, v ; \psi)=\left\{\begin{array}{l}
+\infty, \psi \in K^{*}(X)=E \backslash K(X)  \tag{2.1}\\
W(X ; \psi)+\gamma(\varepsilon, v) \varphi(X, v ; \psi), \quad \psi \in K(\lambda)
\end{array}\right.
$$

Here

$$
\begin{equation*}
\varphi(X, v ; \psi)=\max \{0, h(X, v ; \psi)\}, \quad h(X, v ; \psi)=W(P(v) ; \psi)-\lambda(v) W(X ; \psi) \tag{2.2}
\end{equation*}
$$

Proof. By virtue of (1.2) it is enough to verify the inclusion $\Gamma(\varepsilon, X, v) \subset B(\varepsilon, X, v)$ and the convexity of $\Gamma(\varepsilon, X, v)$. Both these follow from the identity

$$
\begin{equation*}
f(\tau, v) \equiv 1-\lambda(v) \gamma(\tau, v) \tag{2.3}
\end{equation*}
$$

Indeed, for any $z=f(\tau, v) x+\gamma(\tau, v) p$ such that $\tau \in[0, \varepsilon I, x \in X, p \in P(v)$, we have from (2.3) the representation

$$
z=(1-u) x+\alpha(/(\varepsilon, v) x+\gamma(\varepsilon, v) p) \in B(\varepsilon, X, v) ; 0 \leqslant \alpha=\frac{\gamma(\tau, \dot{v})}{\gamma(\varepsilon, v)} \leqslant 1
$$

To verify the convexity of $\Gamma(\varepsilon, X, v)$ we take further

$$
z^{*}-f\left(\tau^{*}, v\right) x^{*}-1 \gamma\left(\tau^{*}, v\right) p^{*} ; \mathfrak{\tau}^{*} \in[0, \varepsilon], x^{*} \in X, p^{*} \in P(c)
$$

Since for any $\mu \in[0,1]$ we can find (because of the continuity of $\gamma(s, v)$ with respect to $s \in[0$, e]) $\tau_{*} \in[0, \varepsilon]$ such that (see (2.3))
we have $\quad \mu \gamma(\tau, v)+(1-\mu) \gamma\left(\tau^{*}, v\right)=\gamma\left(\tau_{*}, v\right)$,
$x_{*}=\beta x+(1-\beta) x^{*} \in X ; \beta=\mu(\tau, v) / f\left(\tau_{*}, v\right) \in[0,1], \quad p_{*}=\omega p+(1-\omega) p^{*} \in P(v) ; \omega=\mu \gamma(\tau, v) / \gamma\left(\tau_{*}, v\right) \in[0,1]$ and, hence

$$
\mu z+(1-\mu) z^{*}=f\left(\tau_{*}, v\right) x_{*}+\gamma\left(\tau_{*}, v\right) \rho_{*} \in \Gamma(\varepsilon, X, v)
$$

The convexity of $\Gamma(\varepsilon, X, \nu)$ has been proved, and with it the first part of the lemma, from which (the closedness of $\Gamma(\varepsilon, X, v)$ follows from that of $P(v)$ follow formulas (2.1), (2.2).

Lemma 3. The set $\Theta_{e}(X)$ is convex and closed. The inclusion $z \in \Theta_{2}(X)$ is fulfilledif and only if

$$
\begin{gather*}
(z \cdot \psi) \leqslant \inf _{n \in Q} W^{\varepsilon}(X, v ; \psi) \equiv \bar{W}^{\varepsilon}(X ; \psi), \quad \forall \psi \in E, \quad \bar{W}^{\varepsilon}(X ; \psi)=W(X ; \psi)+\Phi(X, \varepsilon ; \psi)  \tag{2.4}\\
\Phi(X, \varepsilon ; \psi)=0, \quad \psi \in K^{*}(X) ; \quad \Phi(X, \varepsilon ; \psi)=\max \{0, H(X, \quad \varepsilon ; \psi)\}, \psi \in K(X) \\
H(X, \varepsilon ; \psi)=\min _{v \in Q} \gamma(\varepsilon, v) h(X, v ; \psi) \tag{2.5}
\end{gather*}
$$

Lemma 3 is a trivial corollary of (1.2) and Lemma 2. From (2.4) it follows that the support function $W^{e}(X ; \psi)=W\left(\Theta_{\varepsilon}(X) ; \psi\right)$ of set $\Theta_{\varepsilon}(X)$ is given /7/ by the formula

$$
\begin{equation*}
W^{e}(X ; \psi)=\inf \sum_{i=1}^{m} \bar{W}^{\underline{z}}\left(X ; \psi_{i}\right) \tag{2.6}
\end{equation*}
$$

where the lower bound is taken over all finite collections of vectors

$$
\begin{equation*}
\psi_{i} \in E, \quad i=1, \ldots, m \quad\left(\psi_{1}+\ldots+\psi_{m}=\psi\right) \tag{2.7}
\end{equation*}
$$

We observe that, as follows from (2.1) and (2.6)

$$
\begin{equation*}
K(X)=K\left(\Theta_{e}(X)\right), \quad \varepsilon \geqslant 0 \tag{2.8}
\end{equation*}
$$

3. We denote

$$
S^{+}(X)=\left\{\psi \in K(X): \inf _{v \in Q} h(X, v ; \psi)>0\right\} ; \quad S^{+}=S^{+}(M)
$$

Lemma 4. If $\psi \in K(X)$, then $\psi \notin S^{+}(X)$ if and only if

$$
\begin{equation*}
\Phi(X, \varepsilon ; \psi)=0, \quad \forall \varepsilon \geqslant 0 \tag{3.1}
\end{equation*}
$$

The proof follows trivially from the inequality $\gamma(\varepsilon, v)>0$ for $\varepsilon>0$ and $v \in Q$.
Lemma 5. If $\psi \notin S^{+}(X)$, then the inequalities

$$
\begin{align*}
& W^{\tau}(X ; \psi) \equiv W(X ; \psi), \quad \Phi\left(\Theta_{\tau}(X), t ; \psi\right) \equiv 0  \tag{3.2}\\
& W\left(\Theta_{\omega_{t}}(X) ; \psi\right) \equiv W(X ; \psi), \quad \Phi\left(\Theta_{\omega_{t}}(X), \tau ; \psi\right) \equiv 0 \\
& W\left(\Theta_{t}^{*}(X) ; \psi\right) \equiv W(X ; \psi), \quad \Phi\left(\Theta_{t}^{*}(X), \tau ; \psi\right) \equiv 0
\end{align*}
$$

Proof. By virtue of (1.2)

$$
\begin{equation*}
X \subset \theta_{t}^{*}(X) \subset \theta_{\omega_{t}}(X) \subset \theta_{t}(X) \tag{3.3}
\end{equation*}
$$

Therefore, equalities (3.2) are obvious for all $\psi \in K^{*}(X)$. If now $\boldsymbol{p} \in \boldsymbol{K}(X)$, then from (3.3) we have $W(X ; \psi) \leqslant W^{\tau}(X ; \psi)$ which together with (2.6) yields (cf. (3.1))

$$
W(X ; \psi) \leqslant \overline{W^{\tau}}(X ; \psi)=W(X ; \psi)+\Phi(X, \tau ; \psi)=W(X ; \psi), \psi \notin S^{+}(X)
$$

The first equality in (3.2) has been proved. With due regard to (2.2), (2.4), (2.5) we then obtain $\Phi\left(\Theta_{\tau}(X), t ; \psi\right)=\Phi(X, t ; \psi)$, but the latter expression equals zero by Lemma 4. The first row of equalities in (3.2) has been proved. From it, in accord with (2.8), follows the inclusion

$$
\begin{equation*}
S^{+}\left(\theta_{\tau}(X)\right) \subset S^{+}(X) \tag{3.4}
\end{equation*}
$$

for any convex closed set $X \subset E$ and for $\tau \geqslant 0$. Hence by induction

$$
\begin{equation*}
S^{+}\left(\boldsymbol{\theta}_{\omega_{t}}(X)\right) \equiv S^{+}\left(\theta_{\delta_{m}}\left(\ldots\left(\theta_{\delta_{1}}(X)\right) \ldots\right)\right) \subset S^{+}(X), \quad \forall \omega_{t} \in \Omega_{t}, t \geqslant 0 \tag{3.5}
\end{equation*}
$$

in connection with which the second row of equalities in (3.2) is fulfilled. Hence, with due regard to (3.3), (2.2), (2.5) and Lemma 4 we have

$$
W(X ; \psi) \leqslant W\left(\Theta_{t}^{*}(X) ; \psi\right) \leqslant W\left(\theta_{\omega_{t}}(X) ; \psi\right)=W(X ; \psi), \quad \Phi\left(\theta_{t^{*}}(X), \tau ; \psi\right)=\Phi(X, \tau ; \psi)=0
$$

4. Let

$$
\lambda^{*}=\max _{v \in Q} \lambda(v) ; \quad f(\varepsilon)=\exp \left(-\lambda^{*} \varepsilon\right) ; \quad \gamma(\varepsilon)=\int_{0}^{e} f(r) d r ; \quad W(\psi)=\min _{v \in Q} W(P(v) ; \psi)
$$

By $Q^{+}=Q^{+}(M)$ we denote a subset of $Q$ such that for each $\psi \in S^{+}$we can find $\bar{v} \in Q^{+}$satisfying the equality

$$
\begin{equation*}
\min _{v \in Q} h(M, v ; \psi)=h(M, \bar{v} ; \psi) \tag{4.1}
\end{equation*}
$$

We assume the fulfillment of the following condition for pursuit problem (1.1).
Condition A. $\lambda(\bar{v}) \equiv \lambda^{*} \quad$ for any $\quad \bar{v} \in Q^{+}$.
Let $\psi \in S^{+} \equiv S^{+}(M)$. We fix and denote by $\bar{v}=\bar{v}(\psi)$ an arbitrary vector from $Q^{+}$, given by formula (4.1). Let $X \subset E$. We set

$$
\begin{aligned}
& W_{*}(\psi)=W(P(\bar{v}(\psi)) ; \psi) ; \quad H(X ; \psi)=W_{*}(\psi)-\lambda^{*} W(X ; \psi) \\
& \Phi(X ; \psi)=\max \{0, H(X ; \psi)\} ; \quad \Phi_{e}(X ; \psi)=\Phi\left(\theta_{\mathrm{e}}(X) ; \psi\right)
\end{aligned}
$$

Lemma 6. If condition $A$ is fulfilled, then

$$
\begin{equation*}
\bar{W}^{\varepsilon}\left(\Theta_{0}(M) ; \psi\right)=W\left(\Theta_{0}(M) ; \psi\right)+\gamma(\varepsilon) \Phi\left(\Theta_{\delta}(M) ; \psi\right), \quad \forall \psi \in S^{+}, \quad \varepsilon \geqslant 0, \quad \delta \geqslant 0 \tag{4.2}
\end{equation*}
$$

Let us first prove that if $\psi \in S^{+}$and $\delta \geqslant 0$, then

$$
\begin{equation*}
\min _{v \in Q} h\left(\Theta_{\delta}(M), v ; \psi\right)=h\left(\Theta_{\delta}(M), \bar{v}(\psi) ; \psi\right)=H\left(\Theta_{\delta}(M) ; \varphi\right) \tag{4.3}
\end{equation*}
$$

Indeed, by Condition A

$$
\begin{gathered}
W_{*}(\psi)-\lambda^{*} W^{\delta}(M ; \psi)=h\left(\Theta_{\delta}(M), \tilde{v}(\psi) ; \psi\right) \geqslant \min _{v \in Q}\left[W(P(v) ; \psi)-\lambda(v) W^{\delta}(M ; \psi)\right] \geqslant \min _{v \in \mathbb{Q}}[W(P(v) ; \psi) \quad \lambda(v) W(M ; \psi)]+ \\
\quad \min _{v \in Q}\left\{\lambda(v)\left[W(M ; \psi)-W\left(\Theta_{\delta}(M) ; \psi\right]\right\}=h(M, \bar{v}(\psi) ; \psi)+\lambda^{*}\left[W(M ; \psi)-W\left(\Theta_{0}(M) ; \psi\right)\right]=H\left(\Theta_{\delta}(M) ; \psi\right)\right.
\end{gathered}
$$

Equality (4.3) has been proved. Using this equality and the property of the minimum of a product of nonnegative functions, we obtain (see (3.4))

$$
\begin{aligned}
& \gamma(\varepsilon) H\left(\Theta_{\delta}(M) ; \psi\right)=\gamma(\varepsilon, \bar{v}(\psi)) h\left(\Theta_{\delta}(M), \bar{v}(\psi) ; \psi\right) \geqslant I\left(\Theta_{\delta}(M), \varepsilon ; \psi\right) \geqslant \min _{v \in Q} \gamma(\varepsilon, v) \cdot \min _{v \in Q} h\left(\Theta_{\delta}(M), v ; \psi\right)= \\
& \quad \gamma(\varepsilon) H\left(\Theta_{\delta}(M) ; \psi\right), \quad \mathrm{V}_{\psi \in S^{+}\left(\Theta_{\delta}(M)\right)}
\end{aligned}
$$

Consequently, $H\left(\Theta_{\delta}(M), \varepsilon ; \psi\right)=\gamma(\varepsilon) H\left(\Theta_{\delta}(M) ; \psi\right)$ and, hence,

$$
\begin{equation*}
\Phi\left(\Theta_{\delta}(M), \varepsilon ; \psi\right)=\gamma(\varepsilon) \boldsymbol{\top}\left(\Theta_{\delta}(M) ; \psi\right), \forall \psi \equiv S^{+}\left(\Theta_{\delta}(M)\right) \tag{4.4}
\end{equation*}
$$

Now if $\psi \in S^{+} \backslash S^{+}\left(\Theta_{\delta}(M)\right)$, then, by Lemma 4, $\Phi\left(\Theta_{\delta}(M), \varepsilon ; \psi\right)=0$ i.e.,

$$
\min _{v \in Q} h\left(\theta_{\delta}(M), v ; \psi\right) \leqslant 0
$$

which by virtue of (4.3) implies $H\left(\Theta_{\delta}(M) ; \psi\right) \leqslant 0$, so that $\Phi_{\delta}(\eta ; \psi)=0$. Thus we have proved that (4.4) is true for all $\psi \in S^{+}$. From this equality and (2.4) follows (4.2). We set $\Phi(M ; \psi)=0$, $\notin \notin S^{+}(M)$.
5. Lemma 7. Let $\varepsilon \geqslant 0, \psi \in K(M)$. Then for any $\Delta>0$ can find a collection (2.7) such that

$$
\begin{equation*}
0 \leqslant-W^{-c}(M ; \psi)+\sum_{i=1}^{m}\left[W\left(M ; \psi_{i}\right)+\gamma(\varepsilon) \Phi\left(M ; \psi_{i}\right)\right] \leqslant \Delta \tag{5.1}
\end{equation*}
$$

$$
\begin{equation*}
\Phi_{\varepsilon}(M ; \psi) \geqslant f(\varepsilon) \sum_{i=1}^{m} \Phi\left(M ; \psi_{i}\right)-\Delta\left|\lambda^{*}\right| \tag{5.2}
\end{equation*}
$$

Proof. If $W^{\ell}(M ; \psi)-W(M ; \psi)+\gamma(\varepsilon) \Phi(M ; \psi)$, then inequality (5.1) is fulfilled for a collection (2.7) in which $m=1, \psi_{1}=\psi$. Let us verify (5.2). We estimate $H \equiv H\left(\Theta_{\varepsilon}(M) ; \psi\right)$. We have

$$
\begin{align*}
& H==W_{*}(\psi)-\lambda^{*} W^{\varepsilon}(M ; \psi)=W_{*}(\psi)-\lambda * W(M, \psi)-\lambda * \gamma(\varepsilon) \mathrm{D}(M ; \psi)=  \tag{5.3}\\
& \quad H(M ; \psi)-\lambda * \gamma(\varepsilon) \Phi(M ; \psi)=\left\{\begin{array}{l}
!(\varepsilon)(\mathrm{D}(M ; \psi), H(M ; \psi)>0 \\
I(M ; \psi), H(M ; \psi) \leqslant 0
\end{array}\right.
\end{align*}
$$

Hence, $\Phi_{\varepsilon}(M ; \psi)=f(\varepsilon) \Phi(M ; \psi)$ and (5.2) is proved. Consider the case

$$
\begin{equation*}
W^{\varepsilon}(M ; \psi)<W(M ; \psi)+\gamma(\varepsilon) d(M ; \psi) \tag{5.4}
\end{equation*}
$$

By virtue of (3.2), (4.4) we have from this that $\Phi(M ; \psi)>0$, so that

$$
\begin{equation*}
\Phi(M ; \psi)=H(M ; \psi) \tag{5.5}
\end{equation*}
$$

From (5.4), the definition of the lower bound (2.6), and formula (4.2) follows the existence of a collection (2.7) such that (5.1) and the inequality

$$
\begin{equation*}
\sum_{i=1}^{m}\left[W\left(M ; \psi_{i}\right)+\gamma(\varepsilon) \Phi\left(M ; \psi_{i}\right)\right] \leqslant W(M ; \psi) \div \gamma(\varepsilon) \oplus(M ; \psi) \tag{5.6}
\end{equation*}
$$

are fulfilled. Because of the convexity of the support function $W(M ; \psi) \leqslant \sum_{i=1}^{m} W\left(M ; \psi_{i}\right)$, from
$(5.6)$ we have

$$
\begin{equation*}
\sum_{i=1}^{m} \Phi\left(M ; \psi_{i}\right) \leqslant \Phi(M ; \psi) \tag{5.7}
\end{equation*}
$$

Once again we estimate $\boldsymbol{H}$.
Case 1. $\lambda^{*} \geqslant 0$. From (5.3)- (5.5) follows

$$
\Phi_{\mathrm{e}}(M ; \psi) \geqslant H=W_{*}(\psi)-\lambda^{*} W^{\varepsilon}(M ; \psi) \geqslant W_{*}(\psi)-\lambda^{*} W(M ; \psi)-\lambda^{*} \gamma(\varepsilon) \Phi(M ; \psi)==f(\varepsilon) \Phi(M ; \psi)
$$

which together with (5.7) yields (5.2).
Case 2. $\lambda^{*}=-\left|\lambda^{*}\right|<0$. To estimate $H$ we use (5.1), the convexity of $W(M ; \psi)$ and (5.7) $\left.H \geqslant W_{*}(\psi)+|\lambda *|\left\{\sum_{i=1}^{n}\left[\begin{array}{l}W \\ m\end{array} M_{i}\right)+\gamma(e) \Phi\left(M ; \psi_{i}\right)\right]-\Delta\right\} \geqslant W_{*}(\psi)+$ $\left|\lambda^{*}\right| W(M ; \psi)+|\lambda * *|(\varepsilon) \sum_{i=1}^{m} \Phi\left(M ; \psi_{i}\right)-\Delta\left|\lambda^{*}\right|=\Phi(M ; \psi)-\lambda * \gamma(\varepsilon) \sum_{i=1}^{m} \Phi\left(M ; \psi_{i}\right)-\Delta\left|\lambda^{*}\right| \geqslant f(\xi) \sum_{i=1}^{m} \Phi\left(M ; \psi_{i}\right)-\Delta|\lambda *|$
Hence follows (5.2).
6. Theorem 1. If Condition A is fulfilled for problem (1.1), then (1.3) is fulfilled for any $\varepsilon \geqslant 0$

Proof. By virtue of Lemmas 1 and 3 it suffices (see Section l) to verify the inequality

$$
\begin{equation*}
\bar{W}^{\varepsilon_{1}}\left(\Theta_{\varepsilon_{1}}(M) ; \psi\right) \geqslant W^{\varepsilon_{1}+\varepsilon_{1}}(M ; \psi) ; \quad \psi \in E, \quad \varepsilon_{1} \geqslant 0, \quad \varepsilon_{2} \geqslant 0 \tag{6.1}
\end{equation*}
$$

If $\psi \in K^{*}(M)$ or $\psi \in K(M) \backslash S^{+}$, then (6.1) follows from (2.8) or (3.2), respectively. Now let $\psi \in S^{+}, \Delta>0$. In accord with Lemma 7 a collection (2.7) exists such that inequalities (5.1) and (5.2) are fulfilled for $\varepsilon=\varepsilon_{9}$, combining which we obtain

$$
\begin{align*}
& \bar{W}^{\varepsilon_{1}}\left(\Theta_{e_{2}}(M) ; \psi\right)=W^{\varepsilon_{i}}(M ; \psi)+\gamma\left(\varepsilon_{1}\right) \Phi_{\varepsilon_{i}}(M ; \psi) \geqslant \sum_{i=1}^{m}\left[W\left(M ; \psi_{i}\right)+\right.  \tag{6.2}\\
& \left.\quad \gamma\left(\varepsilon_{2}\right) \Phi\left(M ; \psi_{i}\right)\right]-\Delta+\gamma\left(\varepsilon_{1}\right) f\left(\varepsilon_{2}\right) \sum_{i=1}^{m} \Phi\left(M ; \psi_{i}\right)-\gamma\left(\varepsilon_{1}\right) \Delta\left|\lambda^{*}\right|== \\
& \quad \sum_{i=1}^{m}\left\{W^{*}\left(M ; \psi_{i}\right)+\gamma\left(\varepsilon_{1}+\varepsilon_{2}\right) \Phi\left(M ; \psi_{i}\right)\right\}-\Delta\left(1+\gamma\left(\varepsilon_{1}\right)\left|\lambda^{*}\right|\right) \geqslant W^{\varepsilon_{1}+\varepsilon_{i}}(M ; \psi)-\Delta\left(2+f\left(\varepsilon_{1}\right)\right)
\end{align*}
$$

Here we have used relations (4.2), (2.6) and the identity $f(\tau, v) \gamma(s, v)+\gamma(\tau, v) \equiv \gamma(\tau+s, v)$. Since the quantity $\Delta>0$ in (6.2) is arbitrary, inequality (6.1) has been proved and with it the theorem.
7. By $Q^{++}=Q^{++}(M)$ we denote a subset of $Q$ such that for each $\psi \in S^{+}$we can find $\bar{v} \in Q^{++}$for which $W(P(\bar{v}) ; \psi)=W(\psi)$.

Condition B. $\overline{0} \in M$ ( 0 is the null vector in $E) ; \lambda(\bar{c}) \equiv \lambda^{*}$ for any $\bar{v} \in Q^{++}$.
Lemma 8. If Condition $B$ is fulfilled for game (1.1), then Condition $A$ is fulfilled. In this case $W_{*}(\psi)=W(\psi)$.
8. Let a pursuit problem be described by the equation /4/

$$
\begin{equation*}
d z / d t=C z-F(u, v) \tag{8.1}
\end{equation*}
$$

where $C$ is a constant $n$ th-order square matrix, $F(u, v), P, Q$ and $M$ satisfy the requirements
in Sect.l for problem (1.1).
Theorem 2. Equalities (1.3) are fulfilled for problem (8.1) if matrix $C=\lambda^{*} I, \lambda^{*}$ is a real constant, $I$ is the $n$ th-order unit matrix, function $F(u, v)$ is continuous on $p \times Q, P$ and $Q$ are compacts in finite-dimensional spaces, $M$ is a convex closed set.

Proof. If the hypotheses of Theorem 2 are satisfied, then problem (8.1) turns into problem (1.1) in which $\lambda(v) \equiv \lambda^{*}, v \in Q$, in connection with which condition A is fulfilled. It remains to apply Theorem 1 .
9. Theorem 3. If in problem (8.1) each nonzero vector $\psi \in K(M)$ is an eigenvector of matrix $C^{*}$ (the operator adjoint to $C$ ), the equalities (1.3) are fulfilled.

Proof. Since $K(M)$ is a convex cone $/ 7 /$, a single real $\lambda^{*}$ exists such that $C^{*} \psi=\lambda^{*} \psi$ for all $\psi \in K_{0}$, where $K_{0}$ is a subspace, being the linear hull of $K(M)$. If the dimension $n_{*}=\operatorname{dim} K_{0}=n$, then matrix $C^{*}$, and with it also $C$, has the form $\lambda^{*} I$, where $I$ is the $n$ th-order unit matrix. It remains to make use of Theorem 2. Now let $n_{*}<n$. By $N_{0}$ we denote the orthogonal complement to $K_{0}$ in $E$ and by $\pi$ we denote the operator of orthogonal projection onto $K_{0}$. Then the following lemma is valid.

Lenma 9. Set $M$ can be represented as

$$
\begin{equation*}
M=N_{0}+M_{*} ; \quad M_{*}=\pi M \tag{9.1}
\end{equation*}
$$

Proof. At first we verify the set $m_{g}+N_{g}$ is contained in $M$ for any $m_{b} \in M$. To the contrary suppose that we can find $n_{0} \in N_{0}$ such that $m_{0}+n_{0} \notin M$; then by the separability theorem / $7 /$ there exists $\psi \in K(M)$ such that $\left(\psi \cdot\left(m_{0}+n_{0}\right)\right)>(\psi \cdot m)$ for every $m \in M$. Taking $m=m_{0}$ and recalling that $\left(\psi \cdot n_{0}\right)=0$, we arrive at a contradiction. To prove (9.1) it remains to make use of the chain of inclusions

$$
N_{0}+M_{*}=N_{0}+M \subset M \subset N_{0}+M_{*}
$$

We complete the theorem's proof. We set $z_{*}=\pi z ; z^{*}=z-\pi z ; F_{*}(u, v)=\pi F(u, v) ; C_{*}=\pi C$. By virtue of (9.1), $z \in M$ if and only if $z_{*} \in M_{*}$. Further, since subspace $K_{0}$ is invariant relative to operator $C^{*}$, we have that $N_{0}$ is invariant relative to $C$, so that $C_{*^{2}} \equiv 0$. In addition, for any $\psi \in K_{0}$ we have

$$
\left(\psi \cdot\left[C_{*^{2}} z_{*}-\lambda^{*} z_{*}\right]\right)=\left(\psi \cdot C z_{*}\right)-\lambda^{*}\left(\psi \cdot z_{*}\right)=\left(C^{*} \psi \cdot z_{*}\right)-\lambda^{*}\left(\psi \cdot z_{*}\right)=0
$$

Consequently, $C_{*} z_{*}=\lambda^{*} z_{*}$. Therefore, applying operator $\pi$ to (8.1), we obtain

$$
\begin{equation*}
d z_{*} / d t=\pi(d z / d t)=C_{*}\left(z_{*}+z^{*}\right)-F_{*}(u, v)=\lambda^{*} z_{*}-F_{*}(u, v) \tag{9.2}
\end{equation*}
$$

Thus, under the hypotheses of Theorem 3 game (8.1) is equivalent to game (9.2) with terminal set $M_{*}$. Since game (9.2) already satisfies the hypotheses of Theorem 2, Theorem 3 is proved. Let us now prove a theorem that in some sense is the converse to Theorem 3 .
Theorem 4. Let a matrix $C$ and a convex closed terminal body $M / 8 /$ be such that we can find a vector $\varphi_{0} \in K(M),\left|\varphi_{0}\right|=1$, that is not an eigenvector of operator $C^{*}$. Then for any sufficiently small $\theta_{0}>0$ there exist the spheres $P=a+(\rho+\sigma) S, Q=\rho S(\rho>0, \quad \sigma>0 ; S$ is the closed unit sphere in $E$ with center at the origin; $a$ is a constant vector) and the function $F(u, v)=u-v$ such that in problem (8.1) the sets $T_{\varepsilon}(M)$ and $T_{\varepsilon}{ }^{*}(M)$ do not coincide for some $\varepsilon \in\left(0, \theta_{0}\right)$ (here, as in Theorem 3, we use the general definition $/ 2 /$ of operators $T_{\mathrm{E}}$ and $T_{\mathrm{E}}{ }^{*}$ ).

The theorem is proved in several stages. By $v(\psi)$ and $\omega(\psi)$ we denote (and use subsequently) the vectors occurring in the equalities.

$$
v(\psi) \equiv Q, \quad(\psi \cdot v(\psi))=W(Q ; \psi) ; \quad \omega(\psi) \in \Omega, \quad(\psi \cdot \omega(\psi))=W(\Omega ; \psi)
$$

Lemma 10. Let $Q$ and $\Omega$ be convcx compact bodies not containing segments on the boundary, where only one support hyperplane passes through each point of the boundary of $\Omega$. Then for any $\varepsilon_{0}>0$ there exists $\delta_{0}>0$ such that the inclusion $v+\omega(\psi)+\delta_{0} \varphi \in P=Q+\Omega$ is fulfilled for all $\varphi, \psi \in S,|\psi|=1$, and for all $v \in Q$ satisfying the inequality $|v(\psi)-v| \geqslant e_{0}$.

Proof. By the lemma's hypotheses the vectors $v(\psi)$ and $\omega(\psi)$ are unique. The subsequent argument is by contradiction. Let $\varepsilon_{0}>0$ exists such that for any positive integer $n$ we can find $\psi_{n},\left|\psi_{n}\right|=1, \varphi_{n} \in S ; v_{n} \in Q,\left|v\left(\psi_{n}\right)-v_{n}\right| \geqslant \varepsilon_{0}$, such that $v_{n}+\omega\left(\psi_{n}\right)+\frac{1}{n} \varphi_{n} \neq P$, i.e., the inequality

$$
\begin{equation*}
\left(\psi^{n} \cdot\left[v\left(\psi^{n}\right)+\omega\left(\psi^{\frac{1}{n}}\right)-r_{n}-\omega\left(\varphi_{n}\right)-\frac{1}{n} \varphi_{n}\right]\right)<0 \tag{9.3}
\end{equation*}
$$

is fulfilled for some $\psi^{n} \in E,\left|\psi^{n}\right|=1$. Passing, if necessary, to a subsequence, we can take it that

$$
\Psi_{n \rightarrow \infty} \rightarrow \psi_{0}, \quad \psi^{n} \rightarrow \Psi^{0}, \quad \varphi_{n} \rightarrow \varphi_{0}, \quad\left|\psi_{0}\right|=\left|\psi^{0}\right|=1 \geq\left|\varphi_{0}\right| ; v_{n} \rightarrow v_{0} \Leftarrow Q
$$

Since (because of the absence of segments on the boundary) the functions $v(\psi)$ and $\omega(\psi)$ are continuous /7/.

$$
v\left(\psi_{\boldsymbol{n}}\right) \rightarrow v\left(\psi_{0}\right), \quad v\left(\psi^{n}\right) \rightarrow p\left(\psi^{0}\right), \quad \omega\left(\psi_{n}\right) \rightarrow \omega\left(\psi_{0}\right), \quad \omega\left(\psi^{n}\right) \rightarrow \omega\left(\psi^{0}\right), n \rightarrow \infty
$$

Passing to the limit, from (9.3) we obtain

$$
\begin{gather*}
\left(\psi^{0} \cdot\left[v\left(\psi^{0}\right)-v_{0}\right]\right)+\left(\psi^{0} \cdot\left[\omega\left(\psi^{0}\right)-\omega\left(\psi_{0}\right)\right]\right) \leqslant 0  \tag{9.4}\\
\left|v\left(\psi_{0}\right)-v_{0}\right| \geqslant \varepsilon_{0} \tag{9.5}
\end{gather*}
$$

Noting that each of the two terms in the left-hand side of (9.4) are nonnegative, we conclude that $v_{0}=v\left(\psi^{0}\right) ; \omega\left(\psi^{0}\right)=\omega\left(\psi_{0}\right)$. Since only one support hyperplane to $\Omega$ passes through the point $\omega\left(\psi_{0}\right)$, we have that $\psi_{0}=\psi^{\prime \prime}$, so that $v_{0}=v\left(\psi_{0}\right)$, but this contradicts (9.5).
10. Everywhere in this section we assume that in game (8.1) $M$ is a convex closed body, $F(u, v)=u-v, P=Q+\Omega$, where $Q$ and $\Omega$ satisfy the hypotheses of Lemma 10. For any $z_{0} \in E$ we denote by $t\left(z_{0}\right)$ the earliest instant $t \geqslant 0$ for which the inclusion $z_{0} \in T_{t}{ }^{*}(M)$ is fulfilled. It is woll known /9/ that in this case the instant $t\left(z_{0}\right)$ can be defined also as the earliest instant $t \geqslant 0$ for which the inclusion.

$$
\begin{equation*}
\Phi(t) z_{0} \in M+\int_{0}^{t} \Phi(r) \Omega d r ; \quad \Phi(t) \equiv \exp (t C) \tag{10.1}
\end{equation*}
$$

is fulfilled. Using the notation of Lemma 10, we assume

$$
v(r, \psi)=v(w(r, \psi)), \quad \omega(r, \psi)=\omega(w(r, \psi)), \quad w(r, \psi)=\Phi^{*}(r) \psi /\left|\Phi^{*}(r) \psi\right|, \quad \Phi^{*}(r) \equiv \exp \left(r C^{*}\right)
$$

Then vectors $m_{0} \in M$ and $\psi_{0} \in E,\left|\psi_{0}\right|=1$ exist such that

$$
\begin{align*}
& \Phi\left(t\left(z_{0}\right)\right) z_{0}=m_{0}+\int_{0}^{t\left(z_{0}\right)} \Phi(r) \omega\left(r, \psi_{0}\right) d r  \tag{10.2}\\
& \left.\Phi(t) z_{0} \nsubseteq M+\int_{0}^{t} \Phi(r) \Omega d r, \quad t \in 10, t\left(z_{0}\right)\right) \tag{10.3}
\end{align*}
$$

Lemma 11. For the fulfilıment of the equality $T_{\mathrm{E}}(M)=T_{\varepsilon}{ }^{*}(M), \varepsilon \in\left[0, t\left(z_{0}\right)\right]$ it is necessary that the condition (int is the symbol for the interior of a set)

$$
\begin{equation*}
\Phi(t) z_{0}+\int_{0}^{t} \Phi(t-r) v\left(t\left(z_{0}\right)-r, \psi_{0}\right) d r \not \equiv \operatorname{int}\left[M+\int_{0}^{t} \Phi(r) P d r\right] \tag{10.4}
\end{equation*}
$$

be fulfilled for any $t \in\left[0, t\left(z_{0}\right)\right)$.
Proof (by contradiction). Let $\tau \in\left[0, t\left(z_{0}\right)\right)$ exist such that

$$
\begin{equation*}
\Phi(\tau) z_{0}+\int_{0}^{\tau} \Phi(\tau-r) v\left(t\left(z_{0}\right)-r, \psi_{0}\right) d r \in \mathbf{i n t}\left[M+\int_{0}^{\tau} \Phi(r) P d r\right] \tag{10.5}
\end{equation*}
$$

This signifies that we can find $q_{0}>0$ such that for each measurable control $v(t) \in Q, t \in[0, \tau]$, satisfying the inequality

$$
\begin{equation*}
\int_{0}^{\tau}\left|v\left(t\left(\bar{a}_{0}\right)-r, \psi_{n}\right)-v(r)\right| d r \leqslant q_{0} \tag{10.6}
\end{equation*}
$$

we can find a measurable control $u(t) \in P, t \in[0, \tau]$, such that

$$
\begin{equation*}
z(\tau)=\Phi \Phi(\tau) z_{0}-\int_{0}^{\tau} \Phi(\tau-r)[u(r)-\imath(r)] d r \in M \tag{10.7}
\end{equation*}
$$

We assume

$$
\varepsilon_{0}=\frac{q_{0}}{2 \tau}, \quad k_{v}=\frac{q_{n}}{4 Q^{*}}, \quad Q^{*}=\max _{v \in Q, \omega \in \Omega}\{|r|+|\omega|\}
$$

Let a number $\delta_{0}>0$ correspond to $\varepsilon_{0}$ by virtue of Lemma 10 . since $M$ is a body, there exist a vector $\varphi_{*}$ and a number $\mu_{0}>0$ such that /8/
$\left|\varphi_{*}\right| \neq 0 ;\left|\Phi^{-1}(r) \varphi_{*}\right| \leqslant 1,0 \leqslant r \leqslant t\left(z_{0}\right), \quad m_{*}+\mu_{0} S \subset M, m_{*}-m_{0}-k_{0} \delta_{0} \varphi_{*}$
We set $B_{1}=\left|m_{*}\right|+1+Q^{*} / B_{2} ; B_{2}=\|C\|+1 ;\|C\|$ is the norm of matrix $C$. We select a number $s_{0} \in$ ( $\tau, t\left(z_{0}\right)$ ) such that

$$
\begin{equation*}
R_{1}\left[\exp \left(B_{2} \mid t\left(z_{u}\right)-s_{0} J\right)-1\right]<\mu_{0} \tag{10.9}
\end{equation*}
$$

We now consider an arbitrary measurable control $v_{*}=\left\{v(t) \in Q, t \in\left[0, v_{n}\right]\right\}$ not satisfying (10.6). This signifies that a measurable set $V\left(v_{*}\right) \subset[0, \tau]$ exists such that mes $V\left(v_{*}\right)=k_{0}, \mid v\left(t\left(z_{0}\right)-\right.$ $\left.r, \psi_{0}\right)-v(r) \mid \geqslant \varepsilon_{0}, \quad r \in V\left(v_{*}\right) . \quad$ Having defined $v(r) \equiv v\left(t\left(z_{0}\right)-r, \psi_{0}\right), r \in\left(s_{0}, t\left(z_{0}\right)\right)$, we assume

$$
u(r)=\left\{\begin{array}{l}
v(r)+\omega\left(t\left(z_{0}\right)-r, \psi_{0}\right) \mid-\delta_{0} \Phi^{-1}\left(t\left(z_{0}\right)-r\right) \varphi_{*}, r \equiv V^{r}(\iota *) \\
v(r)+\omega\left(t\left(z_{0}\right)-r, \psi_{0}\right), r \equiv\left[0, t\left(z_{0}\right)\right] \backslash V\left(v_{*}\right)
\end{array}\right.
$$

(the possibility for such a choice of $u(r) \in P$ follows from Lemma 10 and (10.8)). Then for such a pair of controls $u(r)$ and $v(r)$ (cf. (10.2))

$$
\begin{equation*}
z\left(t\left(z_{0}\right)\right)=\Phi\left(t\left(z_{0}\right)\right) z_{0}-\int_{0}^{t\left(z_{0}\right)} \Phi\left(t\left(z_{0}\right)-r\right)[u(r)-v(r)] d r=m_{*} \tag{10.10}
\end{equation*}
$$

Having denoted $l(r)=z(r)-m_{*}$, we have

$$
|l(r)|=\left|l\left(t\left(z_{0}\right)\right)-\int_{r}^{t\left(z_{0}\right)}\left[C z(\theta)-\omega\left(t\left(z_{0}\right)-\theta, \psi_{0}\right)\right] d \theta\right| \leqslant B_{2} \int_{r}^{t\left(z_{0}\right)}\left(|l(\theta)|+B_{1}\right) d \theta, \quad r \in\left[s_{0}, t\left(z_{0}\right)\right]
$$

So that by Gronwall's lemma ${ }^{r}$ and formula (10.9)

$$
\left|l\left(s_{0}\right)\right| \leqslant B_{1}\left[\exp \left(B_{2}\left[t\left(z_{0}\right)-s_{0}\right]\right)-1\right]<\mu_{0}
$$

By virtue of (10.8) this signifies that $z\left(s_{0}\right) \in M$. Hence from (10.7) it follows that $z_{0} \in T_{s_{0}}(M)$ (see $/ 2 /$ for the definition of $T_{\varepsilon}$ ); however, by virtue of (10.3), $z_{0} \notin T_{*} *(M)$. A contradiction. The lemma has been proved.
11. We complete the proof of Theorem 4. We consider the analytic functions

$$
\Lambda(r)=\frac{1-e^{-r}}{r}=1-\frac{r}{2!}+\frac{r^{2}}{3!}-\ldots ; Y(r)=\frac{r}{1-e^{-r}}=1+\frac{r}{2}+\frac{r^{2}}{12}+\ldots
$$

whose radil of convergence are $+\infty$ and $2 \pi$, respectively. If $A$ is and arbitrary $n$ th-order matrix, $\|A\|<2 \pi$, , then the matrix-valued functions $\Lambda(A)$ and $Y(A)$ exist and satisfy the relations

$$
\Lambda(A) \cdot Y(A)=I ; \quad t \Lambda(t A)=\int_{0}^{t} \exp (-r A) d r, \quad t \geqslant 0
$$

in connection with which the inverse operator

$$
\begin{equation*}
\left[\int_{0}^{t} \exp (-r A) d r\right]^{-1}=\frac{1}{t} Y(t A) \equiv R(t, A) \tag{11.1}
\end{equation*}
$$

exists for $0<t\|A\|<2 \pi \quad$ Let $m_{0}$ be a fixed point of set $M$ such that $\quad\left(m_{0} \cdot \varphi_{0}\right)=W\left(M ; \varphi_{0}\right)$. Since $M$ is a body, a vector $\varphi_{*},\left|\varphi_{*}\right|=1$, and a number $\mu_{0}>0$ exist such that

$$
\begin{equation*}
m_{0}-\lambda \Phi_{*} \in \operatorname{int} M, \quad \lambda \in\left(0, \mu_{0}\right) \tag{11.2}
\end{equation*}
$$

The vector $\varphi_{0}$ is not an eigenvector of operator $D=C^{*}$. Therefore, the number $\quad \alpha=\left|D \varphi_{0}\right|^{2}-$ $\left(\varphi_{0} \cdot D \varphi_{0}\right)^{2}>0$.

Now let $\theta_{i} \geqslant 0(i=1,2,3,4)$ be arbitrary numbers satisfying the relations

$$
\begin{equation*}
\theta_{4} \in\left(0, \min \left\{1, \frac{\pi}{\|C\|}\right\}\right), \quad \theta_{2}>0, \quad \theta_{3}>0, \quad \theta_{2}+\theta_{3}=\theta_{4}, \quad \theta_{1} \in\left[0, \theta_{4}\right] \tag{11,3}
\end{equation*}
$$

We set $G(x, y)=x \Lambda(x C) \cdot R(y, C)$ and consider the expressions

$$
\begin{aligned}
& g\left(\theta_{1}, \theta_{2}, \theta_{3}\right)=\left(\varphi_{0} \cdot G\left(\theta_{1}, \theta_{2}\right)\left[\chi\left(0, \theta_{3}\right)-\int_{0}^{\theta_{3}} \Phi(r) w\left(\theta_{2}+r, \varphi_{0}\right) d r\right]\right) \\
& \chi(x, y)=\int_{x}^{y} \Phi(r) w\left(r, \varphi_{0}\right) d r, \quad \xi\left(\theta_{1}, \theta_{2}\right)=\left(\varphi_{0} \cdot G\left(\theta_{1}, \theta_{2}\right) \varphi_{*}\right) \\
& \left.x\left(\theta_{1}, \theta_{2}, \theta_{3}\right)=\left(\varphi_{0} \cdot I \chi\left(\theta_{6}-\theta_{1}, \theta_{4}\right)-G\left(\theta_{1}, \theta_{2}\right) \chi\left(\theta_{3}, \theta_{4}\right)\right]\right)
\end{aligned}
$$

The Taylor expansions of these expressions in powers of $\theta_{1}, \theta_{2}, \theta_{3}$ lead to the following estimates ( $N$ denotes a constant depending only on matrix $C$ and not depending on $\theta_{i}(i=1, \ldots, 4)$ ):
$g\left(\theta_{1}, \theta_{2}, \theta_{3}\right) \geqslant \theta_{1} \theta_{3}\left(\frac{\alpha}{2} \theta_{1}-N \theta_{4}^{2}\right) ; \quad \xi\left(\theta_{1}, \theta_{2}\right) \leqslant N \theta_{1} \theta_{2}^{-1}, \quad x\left(\theta_{1}, \theta_{2}, \theta_{3}\right) \geqslant \theta_{1}\left(\frac{\alpha}{12}\left(\theta_{2}-\theta_{1}\right)\left(\theta_{2}-2 \theta_{1}\right)-N \theta_{4}{ }^{2}\left|\theta_{2}-\theta_{1}\right|\right)$
Now let $p>0, q>0, v>0$ be arbitrary real numbers satisfying together with $\theta_{i}(i=1, \ldots$ .,4) the inequalities

$$
\begin{equation*}
v \leqslant p \theta_{2} \theta_{4}{ }^{2}, \quad \theta_{4}<\frac{a}{200 N}, \quad \frac{1}{2} \theta_{4}<\theta_{2}<\frac{2 p}{q}<\frac{\alpha}{100 N} \tag{11.5}
\end{equation*}
$$

From (11.4), (11.5) we have the estimate

$$
\begin{equation*}
\eta\left(p, q, v, \theta_{2}, \theta_{3} ; r\right)>0, \quad r \in\left(0, \theta_{4}\right] \tag{11.6}
\end{equation*}
$$

for the expression $\eta\left(p, q, v, \theta_{2}, \theta_{3} ; r\right)=\frac{1}{r}\left\{p \theta_{3}^{-1} g\left(r, \theta_{2}, \theta_{3}\right)+q \mu\left(r, \theta_{2}, \theta_{3}\right)-v \xi\left(r, \theta_{2}\right)\right\}$.
Let us now consider a game (8.1) in which

$$
\begin{equation*}
F(u, v)=u-v, \quad P=Q+\Omega, \quad Q=\rho S, \quad \Omega=a+\sigma S \tag{11.7}
\end{equation*}
$$

$a=C m^{*}+a_{*}, m^{*}=m_{0}+\sigma \chi\left(0, \theta_{0}\right), a_{*}=R\left(\theta_{0}-\tau, C\right) \times\left\{-v \varphi_{*}+\rho\left[\chi(0, \tau)-\int_{0}^{\tau} \Phi(r) w\left(\theta_{0}-\tau+r, \varphi_{0}\right) d r\right]-\sigma \chi\left(\tau, \theta_{0}\right)\right\}$
and the constants $\rho>0, \sigma>0, \theta_{0}>2 \tau>0, v>0$ satisfy the inequalities

$$
\begin{equation*}
\theta_{0}<\min \left\{1, \pi\|C\|^{-1}, \alpha(200 N)^{-1}\right\}, \quad \frac{100 N}{\alpha}<\frac{\sigma}{2 \rho \tau}<\theta_{0}^{-1}, \quad v<\frac{\sigma \theta_{0} 4}{2} \tag{11.8}
\end{equation*}
$$

We take the point $z_{0}=m^{*}+\theta_{0} \Lambda\left(\theta_{0} C\right) a_{*}$ and we verify that the equality $t\left(z_{0}\right)=\theta_{0}$ is fulfilled for this point and that at instant $\tau$ the inclusion (10.5) is fulfilled with $\psi_{0}=\varphi_{0}$, which by Lemma 11 completes the proof of Theorem 4. It is easily verified that (cf. (10.2))

$$
\Phi\left(\theta_{0}\right) z_{0}=m_{0}+\int_{0}^{\theta_{0}} \Phi(r) \omega\left(r, \varphi_{0}\right) d r ; \quad \omega\left(r, \varphi_{0}\right) \equiv a+\sigma w\left(r, \varphi_{0}\right)
$$

Let us prove (10.3) for all $t \in\left[0, \theta_{0}\right)$. For this it is enough to verify the inequality

$$
\Delta(t) \equiv\left(\Psi_{0} \cdot\left\{\Phi(t) z_{0}-m_{0}-\int_{0}^{t} \Phi(r) \omega\left(r, \varphi_{0}\right) d r\right\}\right)>0, \quad \forall t \in\left[0, \theta_{0}\right\}
$$

Simplifying the expression for $\Delta(t)$, we obtain, using (11.7), (11.8), (11.5), (11.3), (11.6),

$$
\Delta(t)=\left(\varphi_{0} \cdot \int_{0}^{\theta_{0}-t} \Phi(-r) a_{*} d r+\sigma \chi\left(t, \theta_{0}\right)\right)=\left(\theta_{\sigma}-t\right) \times \eta\left(\rho \tau, \sigma, v, \theta_{0}-\tau, \tau ; \theta_{0}-t\right)>0
$$

The equality $t\left(z_{0}\right)=\theta_{0}$ has been proved.
To verify (10.5) with $\psi_{0} \equiv \varphi_{0}$ we make use of (11.7), (11.1), (11.2)

$$
\begin{aligned}
& \Phi(\tau) z_{0}+\int_{0}^{\tau} \Phi(\tau-r) v\left(t\left(z_{0}\right)-r, \varphi_{0}\right) d r=\Phi(\tau) z_{0}+\rho \int_{0}^{\tau} \Phi(\tau-r) w\left(\theta_{0}-r, \varphi_{0}\right) d r=m_{0}-v \varphi_{*}+ \\
& \int_{0}^{\tau} \Phi(r)\left[a+(\rho+\sigma) w\left(r, \varphi_{0}\right)\right] d r \in \operatorname{int}\left[M+\int_{0}^{\tau} \Phi(r) P d r\right]
\end{aligned}
$$

The theorem has been proved.

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